

# AI/DE Trajectory Design

User Manual

#### General Info

- The primary objective of AI/DE is to automate the design of trajectories for oil, gas, and geothermal wells
- AI/DE automates the tasks of drilling engineers and well planners in developing well paths. It takes into consideration anti-collision with offset wells, sets limits for dog leg severity and inclination for different well sections, and ESP placement; the app automatically finds the shortest well path that meets the requirements in minutes
- To generate solutions, artificial intelligence (AI) methods are employed, which may not always yield consistent results. Consequently, each subsequent solution can vary slightly or, at times, significantly from its predecessor
- Anti-collision calculations are based on SPE-67616, SPE-108279, and ISCWSA toolcodes rev 4

### Start New Task

1. To start New Task click New Trajectory	AI/DE								
+ New trajectory	New trajectory								
<ul> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> </ul>	Info 2 Base trajectory 3 Targets 4 Limits 5 AC settings 6 Offset wells	7 Review							
<ul> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> </ul>	General 2. Fill References								
<ul> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> </ul>	Location								
✓ Fence Traver ×	Latitiude (deg)     Longitude (deg)     Altitude (m)       60     0     0     0								
	Geomagnetic reference								
	9.80665 50000 72 0 0 0								
You can click here to change the password	1 Upload a file	Next							
(▲) Test user test@test.a	u can upload Task m JSON file	3. Click Next							

# Base Traj Info





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# Targets

	AI/DE											
+ New trajectory	New trajectory											
<ul><li>✓ Fence Traver ×</li><li>✓ Fence Traver ×</li></ul>	<ul> <li>Info</li> <li>Base trajectory</li> <li>Targets</li> <li>Limits</li> <li>AC settings</li> <li>Offset wells</li> <li>Review</li> <li>Enter the Target</li> </ul>											
<ul> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> </ul>	Target T1         NS (m)         EW (m)         TVD (m)         Inc (deg)         Az (deg)											
<ul> <li>✓ Fence Traver ×</li> <li>✓ Fence Traver ×</li> </ul>	200 20 300 90 180											
<ul> <li>✓ Fence Traver X</li> <li>✓ Fence Traver X</li> </ul>	Production targets       Max vertical deviation (m)         Max vertical deviation (m)       Max lateral deviation (m)         10       1											
	Name NS (m) EW (m) TVD (m)											
	+											
Test user Γ→	Back											

### Section Limits



2. Enter Limits for each Wellbore Section





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#### AC Rules



# Offset Wells



6. Click Next

# Review Task and Run



3. Click To Calculate the Task

### Wait for Result





#### Review Result

	AI/DE		-					
+ New trajectory			Resulting Trajectory				Sv	Switch Plot/AC report
TASKS	MD (m)	Inc (deg)	Az (deg)	NS (m)	EW (m)	TVD (m)	DLS (deg/	3D AC scan
✓ Fence Traver X	0.0	0.00	0.00	0.0	0.0	0.0	0.00	0 Offset 1 0 Offset 2 0 Offset 3 0 Offset 4 0 Offset 5 0 Offset 6 0 Offset 7
✓ Fence Traver X	680.0	30.02	10.17	171.4	30.8	649.3	1.32	
✓ Fence Traver X	1,549.2	32.27	337.05	602.3	-21.7	1,398.6	0.59	.9382000560477.000 Y 0 1.002.088.938200560477-1.000 0 X 1.000 2.088.938200756
✓ Fence Traver ×	1 926 0	53.02	353.99	848.0	-77 4	1 675 1	1.88	
✓ Fence Traver ×	2,226.0	50.04	11.00	1 1 67 0	(4.2	1.021.0	1.00	
✓ Fence Traver X	2,330.0	50.04	11.09	1,107.2	-64.5	1,931.9	1.00	1,000
✓ Fence Traver X	2,849.1	46.58	13.87	1,540.7	18.1	2,272.6	0.24	
✓ Fence Traver ×	3,548.1	59.86	8.29	2,088.9	123.1	2,690.4	0.60	
✓ Fence Traver X	3,994.6	90.00	180.00	2,000.0	200.0	3,000.0	10.00	2,000
Previous Results								3,000
								Interactive 3D Plot
								4,000



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# Abnormal Result

- If you entered conflicting limits (too low DLS, too narrow inclination range, etc.), AI/DE will not be able to find a solution and will produce an abnormal result as in the picture
- If you get something similar to the picture, try restarting the task with relaxed limits

