AI Well Planner

User Manual



General Info

- The primary objective of AI Well Planner is to automate the design of trajectories for oil, gas, and geothermal wells
- AI Well Planner automates the tasks of drilling engineers and well planners in developing well paths. It takes into consideration anti-collision with offset wells, sets limits for dog leg severity and inclination for different well sections, and ESP placement; the app automatically finds the optimal well path that meets the requirements in minutes
- To generate solutions, artificial intelligence (AI) methods are employed, which may not always yield consistent results. Consequently, each subsequent solution can vary slightly or, at times, significantly from its predecessor
- Anti-collision calculations are based on SPE-67616, SPE-108279, and ISCWSA toolcodes rev 4

UI Overview

1. New trajectory button

Start your trajectory planning session here

2. Dashboard & history

Observe status of running tasks. Click to see results of complete ones

3. Profile settings

Click to navigate to profile page where you can change your password

4. Log-out button

End session and return to login page

5. Content area

The most work will be done here

6. Switch theme button Switch between light and dark



Plan New Trajectory

Three options:

1. Fill info manually

The most basic option 7-8 step process

2. Import from COMPASS

Skip several steps from manual workflow by <u>loading base and offset</u> trajectories

3. Import JSON

Load previously saved project (last step) Skip to <u>end</u>

In any case you can freely navigate between steps using stepper or Next/Back buttons and change any values

Info Base trajectory AC settings Offset wells Transport section Costs Production section General Name Length unit Ence Traversal - cost m \$	nfo Base trajectory AC settings Offset wells Transport section Costs Production section
General Name Fence Traversal - cost Location Loc	no base trajectory AC seturings Oriset weins transport section Costs Production section
General Name Length unit Fence Traversal - cost m C Location Image: Cost	
General Name Length unit Fence Traversal - cost	
Name Length unit Fence Traversal - cost m	General
Fence Traversal - cost m C	Name Length unit
Location	Fence Traversal - cost m
Location	
	Location
Latitude (deg) Longitude (deg) Altitude (m)	Latitiude (deg) Altitude (m)
60 O O O O	60 0 0 0
Geomagnetic reference	Geomagnetic reference
G (m/s2) B (nT) Dip (deg) Dec (deg) Grid (deg)	G (m/s2) B (nT) Dip (deg) Dec (deg) Grid (deg)
9,80665 0 50000 0 72 0 0 0 0	9,80665 0 50000 0 72 0 0 0 0

Plan New Trajectory – General information

1. Name your project

Names are important The name will be displayed in dashboard It also defines export filename

2. Select metric unit

Meter or feet Keep in mind that all inputs that follow will be in selected units

3. Location & reference Self-explanatory. Fill the fields

4. Click Next

	Al Well Plann	ner						
SK				New ti	rajectory			
	1 Info	2 Base trajectory	3 AC settings	4 Offset wells	5 Transport section	6 Costs	7 Production section	8 Review
		General _{Name} Fence Traversal - cost	1		Length unit m	2	\$	
		Location Latitiude (deg) 60	Longitude (deg)	Altitude (m)				
		Geomagnetic reference	ce	,	5			
		G (m/s2) 9,80665	B (nT)	Dip (deg)	Dec (deg)	Grid (c	leg)	
		9,80665	50000	72	0	0		
9 [→	1 Import AIWP JSON	Import COMPASS XML						
i.a				Copyright © AI Well Planner	project by MWD STD Inc – 2024.			

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Plan New Trajectory – Base trajectory

If your trajectory continues or splits from existing well you should enter it. If you need set the kick-off point – paste a vertical trajectory here.

Otherwise just skip this step

1. Enter the wellhead

Keep zeroes if you don't know what are you doing

2. Enter MD/Inc/Az

Just copy MD/Inc/Az values from your Excel spreadsheet, place cursor in highlighted area, and paste

3. Enter survey program

If survey program has more than one survey leg then press the + button to add new ones



Plan New Trajectory – AC settings

TASKS

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Here you can tune anticollision defaults. Disabled fields are for information purpose only at the moment

Critical OSF 1.

Recommended range is between 1.0 and 1.5

2. Wellhead uncertainty 0,3 m / 1 ft by default

3. OD of subject & offset wells

Click Next 4.



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Back

Plan New Trajectory – Offset wells

You can add up to 30 offset wells for AC

1. Add offset well Just click the button

2. Enter the name

It is useful when you will be reading AC report

3. Enter the trajectory

See <u>Base trajectory</u>. But in this case pay close attention to wellhead coordinates

4. Click Next



Plan New Trajectory – Transport section

+ NEW TASK

TASKS

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Transport section is a well path between the base trajectory end and T1 target. If you need to set the kick-off point – do it in Base trajectory step

1. Enable & Target

T1 target of the transport section

2. Toolcode

Select a survey error model for the transport section

3. Optimization options

Select what you want to optimize – well path length or cost

4. ESP

If you have ESP section please specify the limits

5. Section limits

If needed please specify the limits for particulars TVD ranges



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6. Click Next

Plan New Trajectory – Costs

TASKS

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If you chose well cost minimization on previous step then you'll be offered this form

1. Add section(s)

Press button to add one section. You can press it multiple times.

2. Enter stop depths

The first section begins at 0. The last section goes to end. Fill in blanks.

3. Casing type & costs Need I say more?

Delete last section 4. In case you press + too many times

AI Well Planner 6 + NEW TASK New trajectory 6 7 8 Info AC settings Offset wells Transport section Costs Base trajectory Production section Review **Drilling sections** Stop TVD (m) Casing type Casing price (\$/m) Drilling price (\$/m) $\hat{}$ \$ $\hat{}$ $\hat{}$ 280 1000 Casing 100 3 Ζ 2000 $\hat{}$ Casing \$ 143 $\hat{}$ 200 $\hat{}$ 2 ×4 End Casing \$ 96 250 $\hat{}$ 3 +1 Back string [→

5 **Click Next**

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Plan New Trajectory – Production section

Production section is a well path through the multiple targets from T1 target or the base trajectory end

1. DLS limits

Please specify DLS limit for the production section

2. AC & Toolcode

If you need to consider AC-calculations for the section please enable and specify the toolcode

3. TVD clearance

If you need to keep the well path inside the corridor please enable and specify TVD deviation

4. Optimization options

You can optimize the well path length or tortuosity. Please select

5. Targets

The targets specify a well path of the production section Add new pressing +, and remove existing pressing X.



+ NEW TASK

TASKS

6. Click Next

You already know where button is



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Back

Next

Plan New Trajectory – R&R (Review and Run)

Finally! The last step!

1. Validation panel

Let AI review your hard work and highlight some issues if there are any.

2. Export

Don't forget to save your project You can return to it later

3. Task summary

If you wish you can review one more time in case that stupid AI missed something (or you just imported some old task)

4. Create Task

It's time to pass hard work to AI and get some coffee while you wait for result



NEW TASK

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Plan New Trajectory – Validation

Sometimes things doesn't go smoothly and you get errors like this

•	Validation error		
	Expand to see a list of problems	1	^
	 limits.esp.tvd Input should be a valid number 		
	 limits.esp.tvdTo Input should be a valid number 		
Dor	n't give up and just go a few steps back and fix them		
If y	ou get a warning like this		
A	Validation warnings		
	Expand to see a list of problems	1	^
	Value error. Distance between targets should be greater than 250 m		

you can proceed, but be warned that results may be not very great

(Press button to expand list of errors)

Plan New Trajectory – Import from COMPASS

The system will ask you to upload COMPASS XML project file and then show you import dialog

1. Select metric unit

Check and select appropriate unit: feet or meter

Keep in mind that all inputs in the project will be using the same unit

2. Choose base trajectory Pick one from wellbores in project

3. Pick offset wells Check wells that will be used in AC

4. Click Import

You'll be redirected to <u>Transport section</u> step

Import COMPASS project		
Length unit		
ft	1	0
Base trajectory	Offsets trajectories	
Well #204 Wellbore #1	Well #204 Wellbore #1	
Well #203 Wellbore #1	Well #203 Wellbore #1	
Well #201 Wellbore #2	Well #201 Wellbore #2	
Well #201 Wellbore #3	Well #201 Wellbore #3	
Well #201 Wellbore #4 7	Well #201 Wellbore #4 3	
Well #201 Wellbore #1	Well #201 Wellbore #1	
Well #202 Wellbore #2 Hor	Well #202 Wellbore #2 Hor	
🔿 Well #202 Wellbore #1 Pilot	Well #202 Wellbore #1 Pilot	
Well #205 Wellbore #1	Well #205 Wellbore #1	
Well #205 Wellbore #1	Well #205 Wellbore #1	
	Imabri	

Dashboard – Wait for result

Starting task redirects to dashboard where you can

1. Wait for result

It can take 5-10 minutes. Then a green checkmark appears. It means that task is finished

2. Browse previous tasks

Click on row (not the X) to see previous results in content area

3. Delete old results



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Dashboard – Review result

+ NEW TASK

Fence Traver

Production .

Fence Traver

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Fence Traver.

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1. Result trajectory

List of stations which leads from surface to target(s)

2. Export to CSV

Save as CSV to import in other software

3. Sub-report switch

One screen is not enough to show all results. Select:

- 3D plot
- AC report
- QC flags
- Costs report

4. Display area

Shows interactive 3D plot by default

AI Well Planner

MD (m)	Inc (deg)	Az (deg)	NS (m)	EW (m)	TVD (m)	DLS (deg/30				
0,0	0,00	0,00	0,0	0,0	0,0	0,0				
456,3	30,08	280,34	21,0	-115,1	435,6	1,9				
1 309,6	34,89	350,85	310,1	-373,0	1 179,9	1,2				
1 936,8	56,71	7,84	753,8	-365,6	1 616,2	1,1				
2 444,0	51,18	21,82	1 148,8	-262,9	1 915,5	0,7				
3 321,2	51,68	18,80	1 791,9	-24,9	2 462,6	0,0				
3 745,8	53,37	18,29	111,3	82,3	2 721,0	0,1				
4 164,8	90,00	180,00	2 000,0	200,0	3 000,0	10,0				



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Dashboard – Review result – Sub-reports

Anti-collision report

3D AC scan	QC Costs				
Name	OSF	C-to-C (m)	Subject MD (m)	Offset MD (m)	^
Offset 1	1,00	40,0	914,2	800,0	
Offset 2	1,86	69,5	812,6	800,0	
Offset 3	2,83	98,6	812,6	700,0	
Offset 4	3,83	122,5	711,1	700,0	
Offset 5	4,94	154,5	711,1	700,0	
Offset 6	6,15	188,4	711,1	700,0	
Offset 7	8,04	303,6	914,2	900,0	
Offset 8	9,39	451,9	1 219,0	1 200,0	
Offset 9	10,04	519,1	1 320,5	1 300,0	
Offset 10	10,64	587,5	1 422,1	1 400,0	
Offset 11	11,20	658,5	1 523,7	1 500,0	
Offset 12	5,44	487,2	2 437,9	2 000,0	
Offset 13	4,53	398,1	2 437,9	2 000,0	
Offset 14	3,51	298,7	2 336,3	1 900,0	
Offset 15	7,40	501,5	1 726,8	1 600,0	
Offset 16	8,06	549,6	1 726,8	1 600,0	
Offent 17	070	E00 0	1 776 0	1 600 0	~

QC flags

3D	AC scan	QC	Costs					
<u> </u>	Transport targ	jet						
ø	Global DLS							
0	Section 1							
<i>©</i>	Section 2							
<i>©</i>	Section 3							

Costs report (only for transport section)

3D AC scan QC Costs

		Drilling		Casing				
#	Length (m)	Price (\$/m)	Cost (\$)	Length (m)	Price (\$/m)	Cost (\$)		
1	1 050,9	100,00	105 090,29	1 050,9	280,00	294 252,81		
2	1 309,7	200,00	261 945,67	2 360,6	143,00	337 570,27		
3	1 638,6	250,00	409 639,04	3 999,2	96,00	383 921,99		
Subtotal			776 675,00			1 015 745,07		
Total						1 792 420,06		

Abnormal Result

- If you entered conflicting limits (too low DLS, too narrow inclination range, etc.), AI/DE will not be able to find a solution and will produce an abnormal result as in the picture
- If you get something similar to the picture, try restarting the task with relaxed limits

